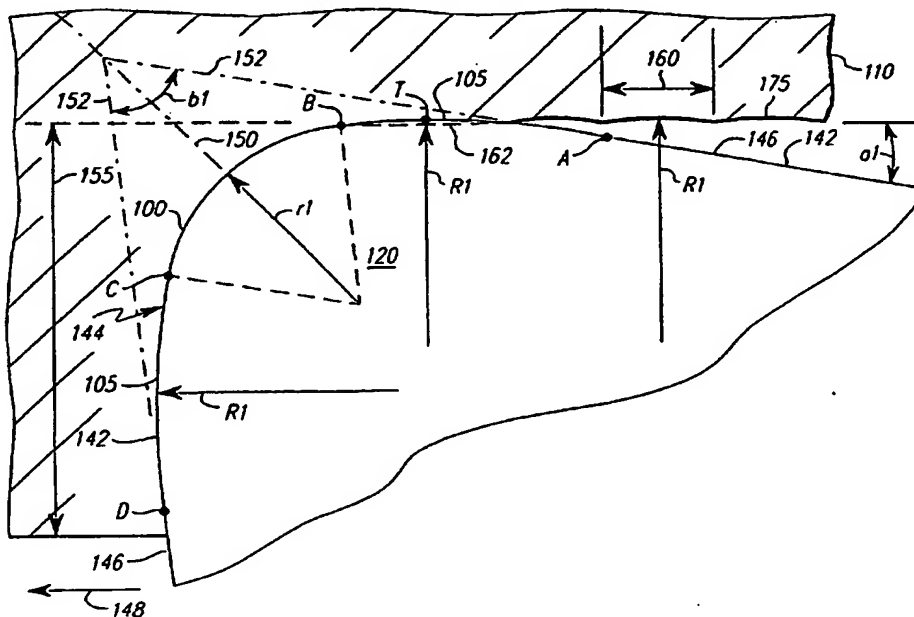




## INTERNATIONAL APPLICATION PUBLISHED UNDER THE PATENT COOPERATION TREATY (PCT)

(51) International Patent Classification <sup>5</sup> : <b>B23B 27/14</b>	<b>A1</b>	(11) International Publication Number: <b>WO 95/00272</b> (43) International Publication Date: <b>5 January 1995 (05.01.95)</b>
(21) International Application Number: <b>PCT/US94/04992</b> (22) International Filing Date: <b>6 May 1994 (06.05.94)</b> (30) Priority Data: 08/083,150                      25 June 1993 (25.06.93)                      US (71) Applicant: <b>KENNAMETAL INC. [US/US]; P.O. Box 231, Latrobe, PA 15650 (US).</b> (72) Inventors: <b>VANKIRK, John, S.; 3727 Windover Road, Murrysville, PA 15668 (US). MASSA, Ted, R.; 53 Orchard Drive, Latrobe, PA 15650 (US). HAMERSKI, Ronald, E.; R.D. 1, Box 293, Ligonier, PA 15658 (US).</b> (74) Agents: <b>PORCELLI, James, G. et al.; Kennametal Inc., P.O. Box 231, Latrobe, PA 15650 (US).</b>		(81) Designated States: <b>AU, CA, JP, KR, RU, European patent (AT, BE, CH, DE, DK, ES, FR, GB, GR, IE, IT, LU, MC, NL, PT, SE).</b> Published <i>With international search report.</i>

(54) Title: INSERT CORNER GEOMETRY FOR IMPROVED SURFACE ROUGHNESS



## (57) Abstract

A cutting insert (120, 140, 210, 610, 510) is disclosed in which at least one corner portion of the insert has a penetrating segment (100, 400, 200, 500, 600) of a given radius for penetrating a workpiece and an adjacent finishing segment (105, 405, 205, 505, 605) having a greater radius or greater radii which follows the penetrating segment to improve the surface roughness of the workpiece.

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## INSERT CORNER GEOMETRY FOR IMPROVED SURFACE ROUGHNESS

BACKGROUND OF THE INVENTION

The present invention generally relates to a cutting insert geometry for use in machining during turning operations. More particularly, the present invention relates to an insert with a modified corner geometry having different radii to provide an improved surface roughness.

Figure 1, which is prior art, shows a typical turning application for machining, in which a workpiece 10 is rotated about a centerline 15 in the direction shown by arrow 17 by a device such as a lathe. A cutting insert 20 may be securely held within a toolholder 25 by means such as a clamp 30 which holds the insert 20 about a mounting pin 32 within the pocket of the toolholder 25.

As seen in Figures 1 and 2, the cutting insert 20 is generally comprised of a polygonal body 34 having a top surface 36 and a bottom surface 38 with a peripheral wall 40 therebetween. A cutting edge 42 is formed at the intersection of the peripheral wall 40 and the top surface 36. A cutting edge 42 may also be formed at the intersection of the peripheral wall 40 and the bottom surface 38.

The insert 20 has at least one corner region 44 which is connected by side segments 46. Figure 3 shows magnified the encircled portion of Figure 1. During a machining operation, the corner

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region 44 contacts the workpiece 10. Additionally, a portion of the side segment 46 of the insert 20 may contact the workpiece 10. To accomplish this, the insert 20 is oriented so that the side segment 46 nearest the trailing edge of the insert 20 is angled away from the workpiece 10 at an angle  $a$ , known as the clearance angle, formed between the side segment 46 and the direction of feed 48, which is the direction the insert 20 is advanced into the workpiece 10 with each revolution of the workpiece 10. From inspection of Figures 1 and 3, it may also be seen that forwardmost portion of the corner region 44 engages the workpiece 10.

The corner region 44 may be symmetric about a bisector line 50, bisecting an angle  $b$  formed by the intersection of a line 52 extended from the cutting edge 42 of each adjacent side segment 46.

The toolholder 25 (Figure 1) is advanced toward the workpiece 10 until the cutting insert 20 penetrates the workpiece 10 surface to a certain depth. The amount the cutting insert 20 penetrates the workpiece 10, measured in a direction normal to the surface of the workpiece, is known as the depth of cut and is identified as item 55 in Figure 3.

The toolholder 25 is also advanced a certain distance with each revolution of the workpiece 10 such that material may be removed along a face of the workpiece 10. This movement occurs in the direction of feed 48 and is known as the feed rate indicated by item 60. Since the feed rate is the distance the insert 20 moves in one revolution of the workpiece 10, the units of feed rate are length.

Generally, cutting inserts, such as insert 20, have a corner region 44 comprised of a curved section of a single radius  $r$  as illustrated between points A and D in Figure 3. As a result of the insert 20 moving across the surface of the

workpiece 10, material is removed from the workpiece 10 and the resulting surface contains a series of peaks 65 and valleys 70 defining scallops 75. As can be seen in Figures 1 and 3, the shape of the corner region 44 of the insert 20, which has radius  $r$ , is imparted to the workpiece 10 and the scallops 75 will, therefore, also have a radius  $r$ . It is the finish created on the workpiece 10 by these scallops which defines the surface roughness of the workpiece 10.

It is generally accepted that the surface roughness produced by an insert is primarily a function of the corner region radius and the feed rate. It can be appreciated that, if the feed rate 60 is decreased, the distance between peaks 65 and the height of each peak 65 will decrease, thereby providing an improved surface roughness.

However, improved surface roughness may also be accomplished by modifying the corner region of the insert. On an insert with a constant radius  $r$  in the corner region 44, the surface roughness, as provided on Page 168 of the book entitled "Fundamentals of Machining and Machine Tools," Second Edition, by Geoffrey Boothroyd and Winston Knight, is closely related to the feed rate and corner region radius by the following expression:

$$\text{Surface roughness} = \frac{0.0321 \times (\text{feed rate})^2}{\text{corner region radius}}$$

where the feed rate is in units of length (per revolution), the corner region radius is in units of length and the surface roughness is in units of length. As an example, if the feed rate is in inches (per revolution) and the corner region radius is in inches, the surface roughness will be in inches.

For the best surface roughness with a fixed feed rate, the corner region radius should be as large as possible. However, the cutting forces on the insert are the smallest when the corner region radius is the

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smallest. If the radius becomes too large, then, while the surface roughness improves the forces acting upon the cutting edge are higher. For this reason, a radius is selected that is a trade-off between these two factors.

5 United States Patent No. 4,990,036, to Ecklund et al., issued February 5, 1991, entitled "Cutting Insert," teaches a cutting insert with a main cutting edge for roughing operations and a secondary cutting edge for finishing operations. However, the secondary cutting edge is separated from the primary cutting edge by a clearance portion and by a difference in elevation, thereby requiring a minimum depth of cut before the primary cutting edge may be engaged and a minimum length of cut before the secondary edge is engaged. Additionally, a separation in distance between the primary and secondary cutting edges makes necessary precise angular positioning of the cutting insert and toolholder relative to the workpiece to properly engage the secondary cutting edge. Such an insert would have limited effectiveness in the corner region of a workpiece.

It is an object of this invention to provide a cutting insert for turning applications which will provide an improved surface roughness over a range of feed rates relative to other inserts using a single radiused corner region and the same feed rates.

It is a further object of this invention to provide a cutting insert that would provide improved surface roughness and be compatible with currently existing toolholders.

It is a further object of this invention to provide a cutting insert which will provide an improved surface roughness and will also be indexable, thereby providing a multiple of corner regions that may be used.

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It is a further object of this invention to provide a cutting insert for turning applications which will provide an improved surface roughness without significantly increasing cutting forces upon the cutting insert.

#### BRIEF SUMMARY OF THE INVENTION

A cutting insert is claimed having a polygonal body of wear resistant material for removing material from a workpiece at a depth of cut along a direction of feed at a feed rate in a turning operation. The cutting insert is comprised of top and bottom surfaces and a peripheral wall therebetween, a cutting edge formed at the intersection of the peripheral wall and the top surface, and at least one corner region and adjacent side segments.

The cutting edge of each corner is comprised of a penetrating segment and a finishing segment. The penetrating segment is defined by a radius and two ends for engaging a portion of the workpiece and producing a surface roughness. The finishing segment is defined by a radius greater than the penetrating segment which intersects with the end of the penetrating segment away from the direction of feed for producing an improved surface roughness.

In a second embodiment, a transition segment is introduced between the finishing segment and the side surface of the insert.

In a third embodiment, a finishing segment is bounded by two penetrating segments to provide the ability to machine in two directions and provide indexability to the cutting insert.

In a fourth embodiment, only one side of the insert cutting edge corner portion includes a finishing segment.

In a fifth embodiment, a surface having a series of continuously increasing radii is substituted for the single radius finishing segment and the

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penetrating segment is reduced in length such that the overall effect of the edge is one of an edge having a continuously increasing radius from a minimum of the penetrating segment radius to a maximum.

5

BRIEF DESCRIPTION OF THE DRAWINGS

The exact nature of the present invention will become more clearly apparent upon reference to the following detailed specification, taken in connection with the accompanying drawings, in which:

10

Figure 1 is prior art showing a plan view of a cutting insert engaging a workpiece in a turning operation.

Figure 2 is prior art showing details in perspective of the insert in Figure 1.

15

Figure 3 is prior art showing the encircled portion of Figure 1 in a magnified view.

Figure 4 is a magnified view of Figure 1, however, modified to show details of the first embodiment of the present invention.

20

Figure 5 shows a plan view of one embodiment of the insert corner portion in the present invention.

Figure 6 illustrates the insert corner portion shown in Figure 5 with permissible angular tolerance.

25

Figure 7 shows a plan view of a second embodiment of a cutting edge of the insert corner portion in the present invention.

Figure 8 illustrates a plan view of the third embodiment of the insert in which the corner portion is again modified.

30

Figure 9 shows details of the corner region of Figure 8.

Figure 10 illustrates a fourth embodiment of the present invention in which the corner region is not symmetrical.

35

Figure 11 illustrates a fifth embodiment in which the finishing segment has a series of



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continuously increasing radii which smoothly blend with the penetrating segment and the side surface.

**DETAILED DESCRIPTION OF THE INVENTION**

With the realization, as shown in

5 Figures 1-3, that the forwardmost portion of the corner region 44 penetrates the workpiece 10 and performs a majority of the cutting, it is then not imperative that portions other than the forwardmost portion of the corner region 44 maintain a relatively small radius  
10 which is ideal for cutting. Instead, the radius of the corner portion 44 away from the direction of feed 48 may be enlarged. Therefore, in accordance with the present invention, the radius for that portion of the corner region which initially penetrates the workpiece  
15 may be sized for optimization in cutting while the radius at the portion of the cutting insert away from that portion which initially penetrates the workpiece 10 may be sized to improve surface roughness. For convenience, the item numbering for different  
20 embodiments of this invention will be similar for similar parts of the prior art elements, but will be incremented by 100 for each embodiment.

Figure 4 shows one embodiment of the present invention in which the cutting insert 120 is comprised  
25 of a corner region 144 bounded by side segments 146 and intersecting the corner region 144 at points A and D. The corner region 144 has a penetrating segment 100 defined between points B and C with a radius  $r_1$ . Furthermore, two finishing segments 105 are adjacent to  
30 the penetrating segment 100 and defined between points A-B and C-D, respectively. Each of the finishing segments 105 has a radius  $R_1$  which is larger than radius  $r_1$  of the penetrating segment 100. One  
35 finishing segment 105 intersects with the side segment 146 to form a clearance angle  $\alpha_1$  between the cutting insert 120 and the direction of feed 148. The depth of cut is shown as item 155.

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It should be noted that insert 120 has two finishing segments 105, one on each side of the penetrating segment 100. For purposes of this discussion, only that finishing segment 105 between points A-B along the workpiece 110 will be discussed with the understanding that the second finishing segment 105 between points C-D may be used for machining in a different direction than that shown by direction of feed 148 such as a direction perpendicular to direction of feed 148.

Furthermore, if the intended direction of feed is in the general direction of feed 148, then the finishing segment 105 between points C-D may be eliminated in favor of extending the penetrating segment 100 past point C to intersect directly with the side segment 146. Such a variation will be discussed with Figure 10.

In Figure 4, the corner region 144 of the insert 120 is symmetric about a bisector line 150 which bisects the angle b1 formed by the intersection of a line 152 extended from the cutting edge 142 of each adjacent side segment 146. This provides symmetry to the corner region 144. While Figure 4 is shown to be symmetric about the bisector line 150, benefits of the subject invention may be fully appreciated without such symmetry. It should further be appreciated that, while R1 in finishing segments 105 defined by A-B and C-D may be approximately equal, that is not required.

As seen in Figure 4, as a result of the present invention, even though the penetration of the workpiece 110 is performed by the penetrating section 100 and by that portion of a side segment 146 facing the direction of feed 148, the surface roughness of the workpiece 110 is a function of radius R1 for the finishing segment 105 between points A-B.

For this finishing segment 105 to engage the workpiece 110 and impart upon the workpiece 110 a

radius  $R_1$ , it is necessary that at least one point T on the finishing segment 105 has a tangent which is parallel to the direction of feed 148 of the cutting insert 120.

5 Under these circumstances, the finishing segment 105 will define the depth of cut 155 because that tangential point parallel to the direction of feed 148 will be the furthestmost projection of the insert 120 into the workpiece 110. This is illustrated  
10 in Figure 4.

Point T in Figure 4 is the point on the finishing segment 105 that is tangential to the direction of feed 148. Improved surface roughness may be provided without the entire length of the finishing segment 105 engaging the workpiece 110. As shown in  
15 Figure 4, the entire portion of the finishing segment 105 forward of point T, that is, the portion on the side of the finishing segment 105 from point T toward the direction of feed 148, along with a portion  
20 of the finishing segment 105 on the opposite side of point T, engage the workpiece 110. As long as at least one portion of the finishing segment 105 engages the workpiece 110, the present invention may be used to improve surface roughness. However it is preferred  
25 that one point of the finishing segment 105 has a tangent which is parallel to the direction of feed 148.

To receive maximum benefits from such a configuration, the feed rate 160 should not exceed the maximum length of a chord 162 on the finishing  
30 segment 105 parallel to the direction of feed 148. A perpendicular line extended from the middle of such a chord 162 should intersect with point T. It is preferred that the finishing segment 105 be centered about this tangential point to maximize the influence  
35 of the finishing segment 105 on the surface roughness.

Figure 5 illustrates the same arrangement as Figure 4 but provides details of radii and relative

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angles for the arcs of the penetrating segment and the finishing segments. It should be noted that if the vector lengths of  $R1$  and  $r1$  shown in Figure 5 were taken to be the actual radii lengths, then  $R1$  would be about three times longer than  $r1$ . However, in actuality, the length of  $R1$  may be up to 50 times greater than the length of  $r1$ . As the radius  $R1$  increases, the cutting forces upon the insert also increase to a point at which the benefit of improved surface roughness is offset by increased forces upon the insert. It should be understood that while generally the force increases as the radius  $R1$  increases, the force is also influenced by the length of the arc on the portion of an insert which contacts the workpiece. An insert with a finishing segment having an arc  $d1$  of 5 degrees and a radius  $R1$  contacting the workpiece will experience lower cutting forces than an insert with a finishing segment having an arc  $d1$  of 15 degrees and a radius  $R1$  which contacts the workpiece. Additionally, as  $d1$  increases, the arc  $c1$  of the penetrating segment 100 will decrease.

It has been found that a CNMG-432 insert, having the following features will provide an improved surface roughness over an unmodified CNMG-432 insert in the same toolholder:

$r1 = 0.03125$  inch                       $c1 = 100$  degrees  
 $R1 = 0.20$  inch                          $d1 = 10$  degrees  
feed rate = 0.020 inch/revolution

With these values, the average surface roughness based on the equation for surface roughness previously discussed, a surface roughness of 64 micro-inches is possible.

As a comparison, using a corner region having a single radius  $r$  of 0.03125 inches and a feed rate of 0.020 inch, the surface roughness is 411 micro-inches. Utilizing this design of the subject invention provides an improvement in surface roughness of 84%.

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It should be noted that the CNMG-432 insert modified in accordance with the present invention was interchangeable with unmodified CNMG-432 inserts. No modifications to other hardware, such as toolholders and insert holding mechanisms, are necessary to receive the benefits of this invention.

Additionally, the present invention, by incorporating a curved surface of a larger radius R1 within the corner region 144, is more forgiving than a straight surface that might be used in lieu of the curved surface for improved surface roughness. If a straight surface were used, then the exact alignment of that surface parallel to the direction of feed would be critical. However, the finishing surface 105 of the present invention is tolerant of angular misalignments such as tolerances inherent within the manufacturing processes of both the toolholder and the insert. While, ideally, the tangential point T should be at the midpoint of the finishing segment 105, thereby providing the greatest amount of finishing segment 105 engaged with the workpiece 110, the insert 120 will still be effective if this is not the case and there is misalignment of the insert or if the direction feed is changed through a range of angular positions of the insert with respect to the workpiece. Such misalignment could be caused by mispositioning of the insert within the toolholder or caused by varying the direction of feed while cutting.

Specifically, as seen in Figure 6, the direction of feed 148' has been slightly angled relative to the insert 120 thereby displacing the tangent point to point T' and defining a chord 162' centered about point T'. As a result, the clearance angle has also changed from  $\alpha_1$  to  $\alpha_1'$ . There is tolerance for angular rotation of the direction of feed 148' relative to the insert 120 when the tangent

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point T' is not at the center of the finishing segment 105.

For reference, Figure 5 is identical to Figure 6 with the exception of the direction of feed 148' and the resultant relative change in orientation between the workpiece 110 and the insert 120.

Even if the feed rate of the insert 120 exceeds the maximum length of the chord 162' on the finishing segment 105 parallel to the direction of feed 148', the present invention will still provide an improved surface roughness. However, the improved surface roughness will be produced by both the penetrating segment radius and the finishing segment radius and the surface roughness will be improved but not to the same degree as that provided with only the finishing segment engaged.

In such cases, referring to Figure 4, there will be portions of the workpiece 110 having scallops 175 with a portion of the scallop 175 having the radius  $r_1$  (not shown) of the penetrating segment 100 and another portion with the radius  $R_1$  of the finishing segment 105 between points A-B. Under these circumstances, it is desirable that the transition shown as point B (Fig. 6) between penetrating segment 100 and the finishing segment 105, be a smooth, continuous transition to prevent any sharp corners from contacting the workpiece. To that end, the slope of the penetrating segment 100 and the finishing segment 105, at their intersection point B, are preferably equal. In the same fashion, if the insert 110 is oriented such that point A, which is the transition point between the finishing segment 105 and the side segment 146, is engaged, then the slope of the finishing segment 105 and the side segment 146, at their intersection point A, are preferably equal.

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In addition to this, some benefit may be received even if no point of the finishing segment 105 is tangent to the direction of the feed, as long as a portion of the finishing segment engages the workpiece 110. The larger radius of the finishing segment 105 will provide an improved surface roughness, relative to that roughness provided by the penetrating segment 100, over any portion of the workpiece 110 it engages.

What has been described in Figures 4-6 is a cutting insert 110 having a corner region 144 with a penetrating segment 100 to engage a workpiece 110 and a finishing segment 105 to improve the surface roughness of the workpiece 110. The finishing segment 105 was blended with the penetrating segment 100 at point B and with the side segment 146 at point A. However, in an alternative embodiment, the finishing segment 105 does not blend directly with the side segment 146.

Figure 7 shows a corner region 244 of an insert 210 having a penetrating segment 200 with radius  $r_2$ , and two finishing segments 205 with radius  $R_2$ .

It is only necessary to provide a finishing segment 205 on the insert 210 of sufficient length to provide for anticipated feed rates. For that reason, and for dimensional control of the location of the penetrating segment 200 on the insert 210, a transitional segment 275 may be introduced between the finishing segment 205 and the side segment 246. Such a segment 275 is bounded by points A and E, and D and F, respectively. The transition segment 275 may have a radius  $R_2'$  which is less than the finishing segment 205 radius  $R_2$ .

The symmetrical configuration of the corner region so far discussed has focused on a single side of that corner region addressing a single direction of feed.

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Unlike Figures 4-6, Figures 8 and 9 illustrate an insert configuration in which a finishing segment 405 is flanked by two penetrating segments 400. Figure 8 shows a cutting insert 420 having a polygonal body 434 with a top surface 436, a bottom surface 438 and a peripheral wall 440 therebetween. A cutting edge 442 is formed at the intersection of the peripheral wall 440 and the top surface 436. A cutting edge may also be formed at the intersection of the peripheral wall 440 and the bottom surface 438. Figure 9 illustrates a magnified portion of Figure 8.

While the insert 420 shape is different from the insert 120 found in Figures 4 and 5, the features are similar in that the penetrating segment 400 initially engages the workpiece 410 and the finishing segment 405 follows to improve the surface roughness of the workpiece 410. The same discussion of the finishing segment function provided earlier applies here.

The cutting insert 420 is comprised of a corner region 444 bounded by side segments 446 and intersecting with these segments at points A' and D'. The corner region 444 has a finishing segment 405 defined between points B' and C' with a radius R3. Furthermore, two penetrating segments 400 are adjacent to the finishing segment 405 and defined between points A'-B' and C'-D', respectively. Each of the penetrating segments has a radius r3 which is smaller than the radius R3 of the finishing segment 405. The penetrating segment 400 between points A'-B' intersects with the side segment 446 to form a clearance angle  $\alpha_3$  between the workpiece 410 and the cutting insert 420.

It should be noted that insert 420 has two penetrating segments 400, one on each side of the finishing segment 405. For purposes of improved surface roughness, only the penetrating segment 400 between points C'-D' along the workpiece 410 will be



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discussed with a direction of feed 448, with the understanding that the second penetrating segment 400 between points A'-B' would be engaged in a similar manner if the direction of feed was directly opposite to that of direction of feed 448. In the alternative, the second penetrating segment 400 between points A'-B' could be eliminated if the only feed occurred within the direction of feed 448.

In order to operate in the direction of feed 448 or opposite to that direction of feed, the corner region 444 is preferably symmetric about a bisector line 450, bisecting an angle b3 formed by the intersection of a line 452 extended from the cutting edge 442 of each adjacent side segment 446. Furthermore, for best performance, the insert 420 should be oriented relative to the workpiece such that the bisection line 450 is perpendicular to the direction of feed 448.

The configuration of insert 420 in Figure 8 and 9 may be similar to that discussed in Figures 4 to 7, but with the substitution of positions for the penetrating segment 400 and finishing segment 405. However, just as before, for improved surface roughness, the penetrating segment 400 will initially contact the workpiece 410 and the finishing segment 405 will follow. For the finishing segment 405 to engage the workpiece 410 and impart an improved surface roughness, it is preferable that at least one point on the finishing segment 405 has a tangent point which is parallel to the direction of feed 448 of the cutting insert 420. However as discussed earlier, it is possible to produce an improved surface roughness by engaging any portion of the finishing segment with the workpiece.

It should be realized in the instant case that the direction of feed 448 could be reversed and the insert 410 would operate just as effectively.

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What has been discussed so far focuses on symmetric corner regions. Figure 10 shows an insert 510 in which the corner region 544 is not symmetric about a bisector line which would bisect an angle formed by the intersection of a line 552 extended from the cutting edge 542 of each adjacent side segment 546. In this instance, the elimination of one finishing segment causes asymmetry in the corner region 544. While finishing segment 505 with radius  $R_4$  exists between points  $A''$  and  $B''$  and a penetrating segment 500 with radius  $r_4$  is adjacent to that between points  $B''$  and  $C''$ , the penetrating segment 500 blends directly with side segment 546 at point  $C''$ . In this instance, improved surface roughness is possible by engaging the finishing segment 505 between points  $A''$ - $B''$  with the workpiece (not shown). For reference, a direction of feed 548 and clearance angle  $a_4$  have been shown with the understanding that, just as before, the tangent of a point along the finishing segment 505 should preferably be parallel to the direction of feed.

So far configurations have been discussed in which the penetrating segment has a single radius and the finishing segment has a larger single radius. It is entirely possible to provide a finishing segment having a plurality of radii greater than that of the penetrating segment increasing from a minimum at the penetrating segment to a desired larger radius which would then blend with the side segment or with a transition segment. Under such circumstances, for example, the insert 120 shown in Figure 4 should have a penetrating segment 100 with radius  $r_1$ , but would then have a finishing segment 105 with radius  $R_1$  at point B and another larger radius  $R_1$  at point A with a series of segments having increasing radii from point B to point A, such that a smooth curve would be presented. Although the surface roughness would improve, the roughness will be a function of the finishing segment

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radius which engages the workpiece. Just as before, it is preferable that at least one point of the finishing segment has a point which is tangential to the direction of feed.

5                   Figure 11 shows such an arrangement. Just as with Figure 10, an insert 610 is shown in which the corner region 644 is not symmetric about a bisector line which would bisect an angle formed by the intersection of line 652 extended from the cutting  
10                   edge 642 of each adjacent side segment 646. This is illustrated as an example with the understanding it is entirely possible for the corner region 644 to have symmetry about a bisector line.

                  A penetrating segment defined by points  
15                   B'''-C''' in the corner region 644 of the insert 610 has a single radius  $r_5$  which blends with the finishing segment 605 defined by points A'''-B'''. The finishing segment 605 is comprised of a curve of continuously increasing radii  $R_5-1$  to  $R_5-n$  with each radius greater  
20                   than that of the penetrating segment 600 to a maximum at the end of the finishing segment 605 away from the penetrating segment 600. Just as before, a smooth continuous transition between the penetrating  
segment 600 and the finishing segment 605 may be  
25                   desired. Under such circumstances, the slope of the penetrating segment 600 and the finishing segment 605, at their intersecting point B''', should preferably be equal. In the same fashion, if the insert 610 is oriented such that point A''', which is the transition  
30                   point between the finishing segment 605 and the side segment 646, is engaged, then the slope of the finishing segment 605 and the side segment 646, at their intersection point A''', should preferably be equal. While not shown in Figure 11, it is possible to  
35                   include in this embodiment a transition segment similar to that discussed with Figure 7 which has a radius less

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than that of the greatest radius of the finishing segment 605.

It is also possible for the finishing segment 605 to occupy a substantial portion of the corner region 644 such that the penetrating segment 600 is greatly diminished relative to the finishing segment 605. Specifically, the arc c5 of penetrating segment 600 may be less than two degrees. Under these conditions, the corner region 644 becomes a continuous curve in which the radius at point C''' is fixed and the curve extending to A''' is comprised of a series of segments with increasing radii to a maximum radius at point A''', which is the end of the finishing segment 605.

With each of these embodiments, it is possible to develop all of the corner regions on a given insert on either the top surface, bottom surface, or both. As such, the insert would be indexable and could also be invertible. However, in the configuration shown in Figure 11, it should be understood that the direction of feed would be limited by the asymmetric nature of the corner region.

What has been described is a cutting insert having a corner region with at least two different radii comprising a penetrating segment to establish an initial surface roughness and a finishing segment to improve such a surface roughness when machining a workpiece.

The present invention may, of course, be carried out in other specific ways than those herein set forth without departing from the spirit and essential characteristics of the invention. The present embodiments are, therefore, to be considered in all respects as illustrative and not restrictive and all changes coming within the meaning and equivalency range of the appended claims are intended to be embraced therein.

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WHAT IS CLAIMED IS:

1. A cutting insert having a polygonal body of wear resistant material for removing material from a workpiece at a depth of cut along a direction of feed at a feed rate in a turning operation comprising:
- 5 (a) top and bottom surfaces and a peripheral wall therebetween;
- (b) a cutting edge formed at the intersection of the peripheral wall and the top surface;
- 10 (c) at least one corner region and adjacent side segments with the cutting edge of each corner region comprised of
- (i) a penetrating segment defined by
- 15 two ends and a radius for engaging a portion of the workpiece and producing a surface roughness and;
- (ii) a finishing segment defined by two ends and a radius greater than the radius of the penetrating segment and intersecting with the end of
- 20 the penetrating segment which is located away from the direction of feed, and
- (iii) the finishing segment further having a point with a tangent parallel to the direction of feed such that when the finishing segment engages
- 25 the same portion of the workpiece an improved surface roughness results.
2. The cutting insert according to claim 1 wherein the maximum length of a chord on the finishing

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segment parallel to the direction of feed is greater than or equal to the feed rate.

3. The cutting insert according to claim 1 wherein a chord connecting the two ends of the finishing segment is parallel to the direction of feed.

4. The cutting insert according to claim 1 wherein the point of the finishing segment with a tangent parallel to the direction of feed defines the depth of cut.

5. The cutting insert according to claim 1 wherein the penetrating segment and the finishing segment are oriented upon the insert so that the slope of each segment at the point of intersection is equal.

6. The cutting insert according to claim 1 wherein the finishing segment and an adjacent side segment are oriented upon the insert so that the slope of each segment at the point of intersection is equal.

7. The cutting insert according to claim 1 further comprising a transition segment between the finishing segment and an adjacent side segment, the transition segment having a radius less than the radius of the finishing segment.

8. The cutting insert according to claim 7 wherein the transition segment and the finishing segment are oriented upon the insert so that the slope of each segment at the point of intersection is equal.

9. The cutting insert according to claim 7 wherein the transition segment and an adjacent side segment are oriented upon the insert so that the slope at the point of intersection is equal.

10. The cutting insert according to claim 1 wherein the radius of the finishing segment is up to fifty times greater than the radius of the penetrating segment.

11. The cutting insert according to claim 1 wherein the configuration of the bottom surface is

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identical to that of the top surface such that the insert is invertible.

12. A cutting insert for advancing against a workpiece in a specific direction of feed during turning applications having a polygonal body of wear resistant material comprising:

(a) top and bottom surfaces and a peripheral wall therebetween;

(b) a cutting edge formed at the intersection of the peripheral wall and the top surface;

(c) at least one corner region and adjacent side regions, each corner region being positioned about a bisector line which bisects an angle formed by the intersection of a line extended from the cutting edge of each adjacent side region, each corner region comprised of

(i) a penetrating segment centered about the bisector line, the penetrating segment having two ends and a radius to enable the associated cutting edge to remove material during penetration into the workpiece at a depth of cut and to generate a scalloped finish on the workpiece and

(ii) a finishing segment immediately adjacent the penetrating segment, opposite the direction of feed, having two ends and a radius greater than that of the penetrating segment and oriented relative to the workpiece such that the tangent of at least one intermediate point on the segment is parallel to the direction of feed and positioned to remove material from the scalloped finish to provide an improved surface roughness.

13. The cutting insert according to claim 12 wherein the maximum length of a chord on the finishing segment parallel to the direction of feed is greater than or equal to the feed rate.

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14. The cutting insert according to claim 12 wherein a chord connecting the two ends of the finishing segment is parallel to the direction of feed.

5 15. The cutting insert according to claim 12 wherein the point of the finishing segment with a tangent parallel to the direction of feed defines the depth of cut.

10 16. The cutting insert according to claim 12 wherein the penetrating segment and the finishing segment are oriented upon the insert so that the slope of each segment at the point of intersection is equal.

15 17. The cutting insert according to claim 12 wherein the finishing segment and an adjacent side segment are oriented upon the insert so that the slope of each segment at the point of intersection is equal.

20 18. The cutting insert according to claim 12 further comprising a transition segment between the finishing segment and an adjacent side segment having a radius less than the radius of the finishing segment.

25 19. The cutting insert according to claim 18 wherein the transition segment and the finishing segment are oriented upon the insert so that the slope of each segment at the point of intersection is equal.

30 20. The cutting insert according to claim 18 wherein the transition segment and an adjacent side segment are oriented upon the insert so that the slope at the point of intersection is equal.

35 21. The cutting insert according to claim 12 wherein the radius of the finishing segment is up to fifty times greater than the radius of the penetrating segment.

22. The cutting insert according to claim 12 wherein the configuration of the bottom surface is identical to that of the top surface such that the insert is invertible.

23. The cutting insert according to claim 12 wherein the corner region includes an additional



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finishing segment which is positioned adjacent the penetrating segment and opposite the first finishing segment such that the entire curve in the corner region is symmetrical about the bisector line.

5                   24. A cutting insert for advancing against a workpiece in a specific direction of feed during turning applications having a polygonal body of wear resistant material comprising:

10                   (a) top and bottom surfaces and a peripheral wall therebetween;

                  (b) a cutting edge formed at the intersection of the peripheral wall and the top surface;

15                   (c) at least one corner region and adjacent side regions, each corner region being positioned about a bisector line which bisects an angle formed by the intersection of a line extended from the cutting edge of each adjacent side region, each corner region comprised of

20                   (i) a penetrating segment centered about the bisector line, the penetrating segment having two ends and a radius to enable the associated cutting edge to remove material during penetration into the workpiece at a depth of cut and to generate a scalloped  
25                   finish on the workpiece and

                  (ii) a finishing segment immediately adjacent the penetrating segment, opposite the direction of feed, the finishing segment having an arc with two ends and a radius greater than that of the  
30                   penetrating segment and oriented such that the tangent of at least one intermediate point on the segment is parallel to the direction of feed and positioned to remove material from the scalloped finish to provide an improved surface roughness, and wherein the finishing  
35                   segment has a chord connecting the two ends which is parallel to the direction of feed, and wherein a point

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of the finishing segment has a tangent parallel to the direction of feed defining the depth of cut.

25. A cutting insert having a polygonal body of wear resistant material for removing material from a workpiece at a depth of cut along a direction of feed at a feed rate in a turning operation comprising:

(a) top and bottom surfaces and a peripheral wall therebetween;

(b) a cutting edge formed at the intersection of the peripheral wall and the top surface;

(c) at least one corner region and adjacent side segments with the cutting edge of each corner region comprised of

(i) a penetrating segment defined by a radius and two ends for engaging a portion of the workpiece and producing a surface roughness and;

(ii) a finishing segment adjacent to the penetrating segment comprised of

(1) a curve with a series of radii with each radius progressively greater than that of the penetrating segment as the distance from the penetrating segment increases, and

(2) a point on the curve with a tangent parallel to the direction of feed for subsequently engaging the portion of the workpiece engaged by the penetrating segment to produce an improved surface roughness.

26. The cutting insert according to claim 25 wherein the point of the finishing segment with a tangent parallel to the direction of feed defines the depth of cut.

27. The cutting insert according to claim 25 wherein the penetrating segment and the finishing segment are oriented upon the insert so that the slope at the point of intersection is equal for each segment.

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28. The cutting insert according to claim 25 wherein the finishing segment and an adjacent side segment are oriented upon the insert so that the slope of each segment at the point of intersection is equal.

5 29. The cutting insert according to claim 25 further comprising a transition segment between the finishing segment and an adjacent side segment having a radius less than the greatest radius of the finishing segment.

10 30. The cutting insert according to claim 29 wherein the transition segment and the finishing segment are oriented upon the insert so that the slope of each segment at the point of intersection is equal.

15 31. The cutting insert according to claim 30 wherein the transition segment and an adjacent side segment are oriented upon the insert so that the slope at the point of intersection is equal.

20 32. The cutting insert according to claim 25 wherein the greatest radius of the finishing segment is no greater than fifty times the radius of the penetrating segment.

25 33. The cutting insert according to claim 25 wherein the configuration of the bottom surface is identical to that of the top surface such that the insert is invertible.

34. A cutting insert having a polygonal body of wear resistant material for removing material from a workpiece at a depth of cut along a direction of feed at a feed rate in a turning operation comprising:

30 (a) top and bottom surfaces and a peripheral wall therebetween;

(b) a cutting edge formed at the intersection of the peripheral wall and the top surface;

35 (c) at least one corner region and adjacent side segments with the cutting edge of each corner region comprised of

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(i) a penetrating segment having a radius and two ends for engaging a portion of the workpiece and producing a surface roughness and;

5 (ii) a finishing segment having two ends and at least one radius greater than the penetrating segment and intersecting with the end of the penetrating segment which is located away from the direction of feed, wherein the at least one radius of the finishing segment is up to fifty times greater than  
10 the radius of the penetrating segment.

35. The cutting insert according to claim 34 wherein the finishing segment is comprised of a series of radii with each radius progressively greater than that of the penetrating segment as the distance from  
15 the penetrating segment increases.

36. The cutting insert according to claim 34 wherein the penetrating segment and the finishing segment are oriented upon the insert so that the slope at the point of intersection is equal for each segment.

20 37. The cutting insert according to claim 34 wherein the finishing segment and an adjacent side segment are oriented upon the insert so that the slope of each segment at the point of intersection is equal.

38. The cutting insert according to claim 34  
25 further comprising a transition segment between the finishing segment and an adjacent side segment having a radius less than the radius of the finishing segment.

39. The cutting insert according to claim 38 wherein the transition segment and the finishing  
30 segment are oriented upon the insert so that the slope of each segment at the point of intersection is equal.

40. The cutting insert according to claim 38 wherein the transition segment and an adjacent side segment are oriented upon the insert so that the slope  
35 at the point of intersection is equal.

41. The cutting insert according to claim 34 wherein the configuration of the bottom surface is

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identical to that of the top surface such that the insert is invertible.

5 42. A method for producing an improved surface roughness on a workpiece during a turning operation comprised of the steps of:

(a) for a cutting insert with a cutting edge having a penetrating segment with a radius and having a finishing segment with a larger radius adjacent the penetrating segment, advancing the insert into a  
10 workpiece in a direction of feed at a feed rate to engage the penetrating segment with the workpiece; and

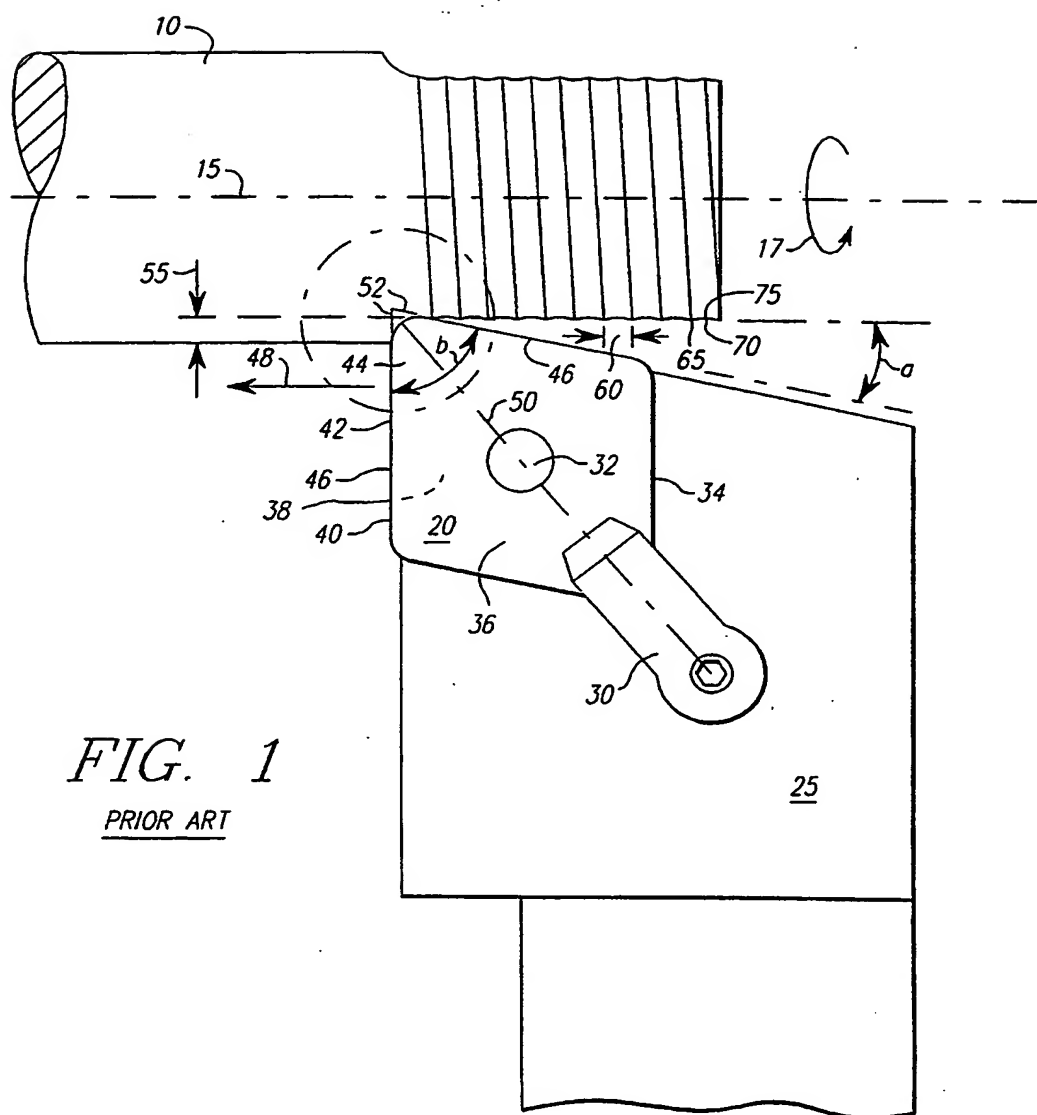
(b) further advancing the insert in the direction of feed to engage the finishing segment thereby providing a larger radius of the cutting edge  
15 acting upon the workpiece resulting in an improved surface roughness.

43. The method of claim 42 further including the step of orienting the insert such that the finishing segment has one point with a tangent parallel  
20 to the direction of feed.

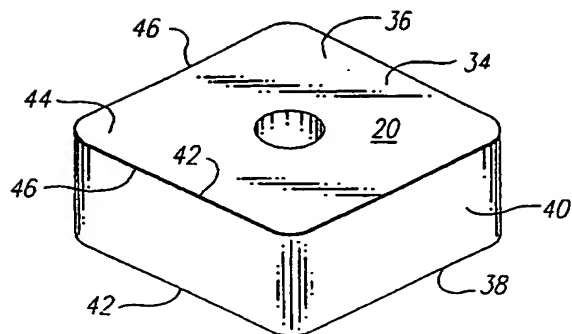
44. The method of claim 43 wherein the step of advancing the insert is comprised of advancing the insert at a feed rate not exceeding the length of a chord on the finishing segment which is parallel to the  
25 direction of feed.

45. The method of claim 43 wherein the step of further advancing the insert is comprised of advancing the insert so that a portion of the finishing segment is at the depth of cut.

30 46. The method of claim 42 wherein the radius of the finishing segment is up to fifty times greater than the radius of the penetrating segment.



*FIG. 1*  
PRIOR ART



*FIG. 2*  
PRIOR ART

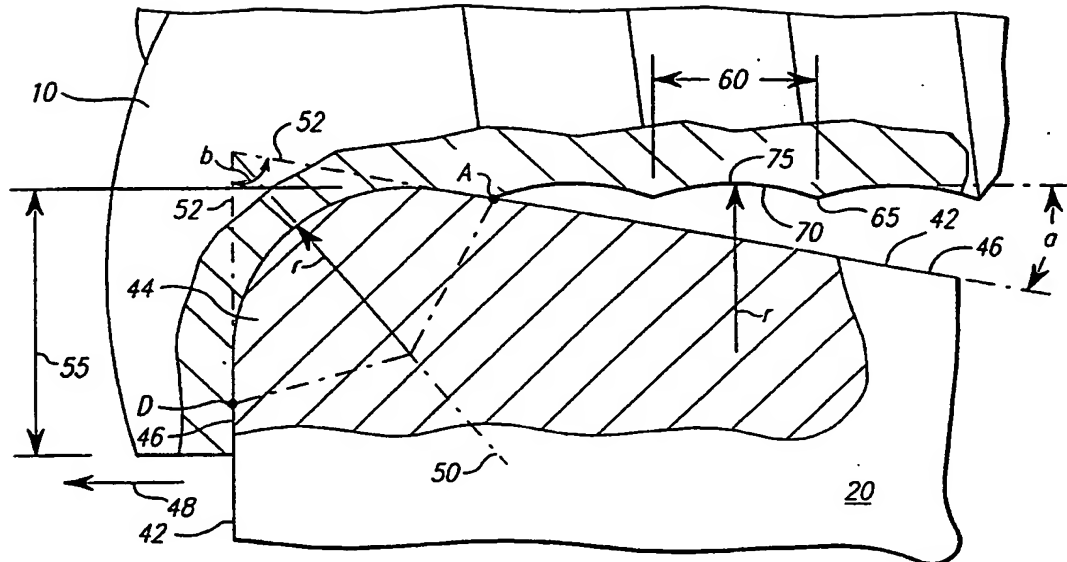


FIG. 3

PRIOR ART

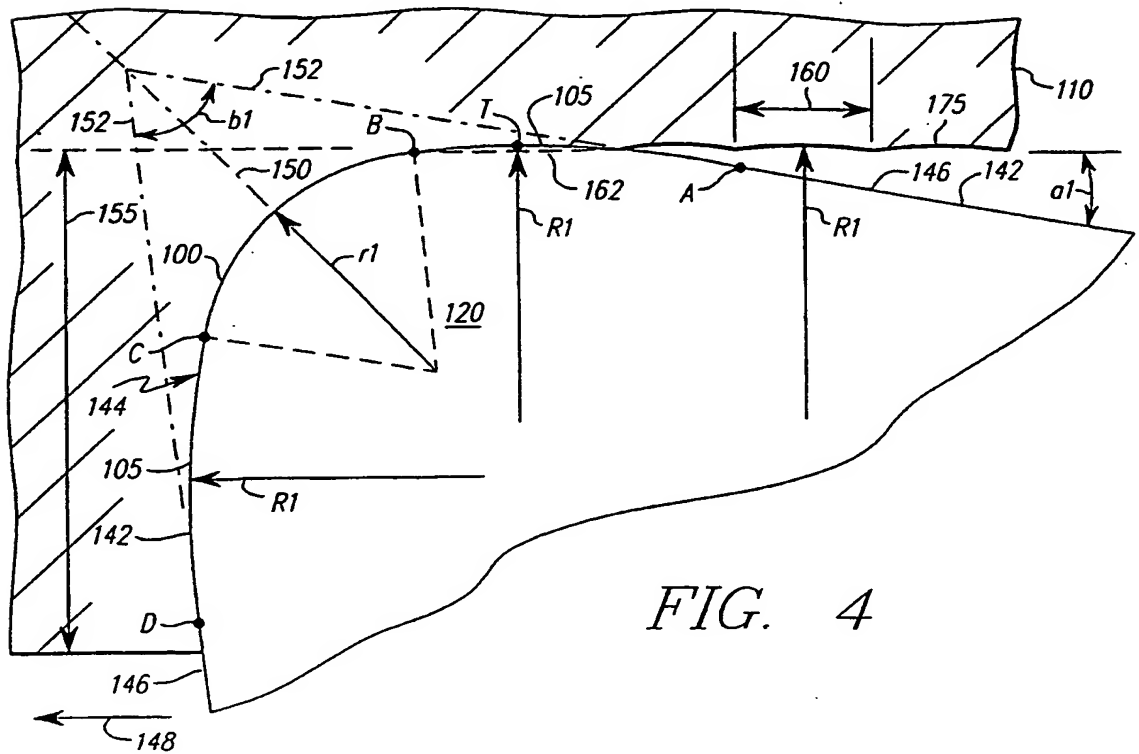


FIG. 4

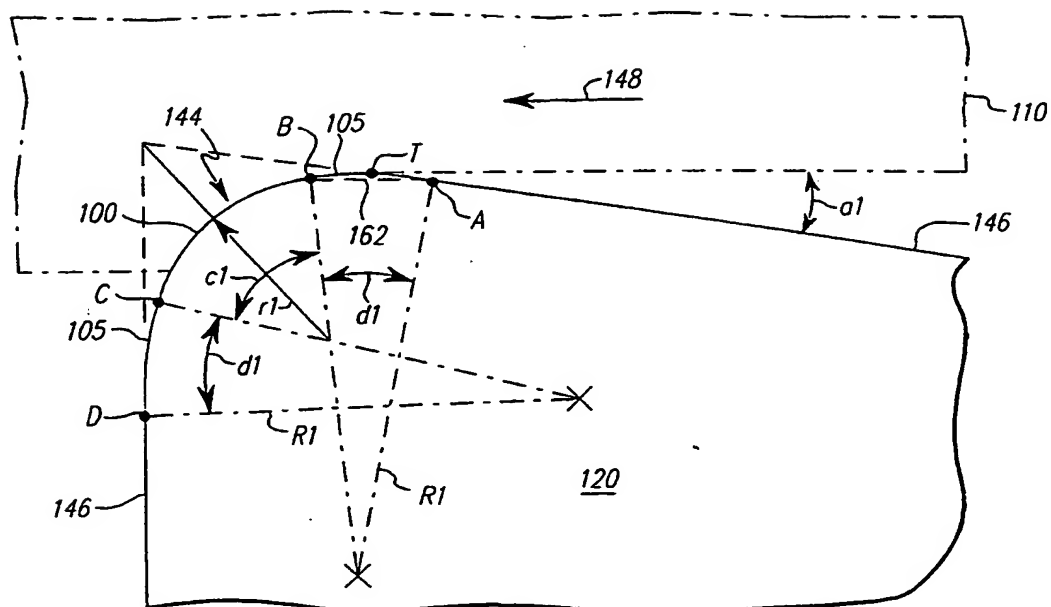


FIG. 5

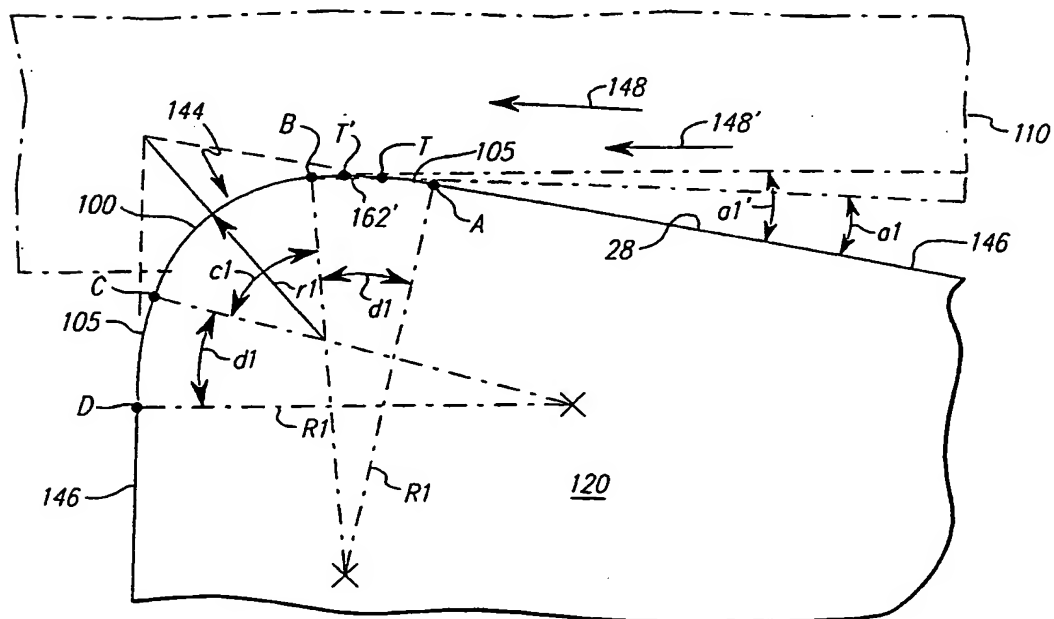


FIG. 6



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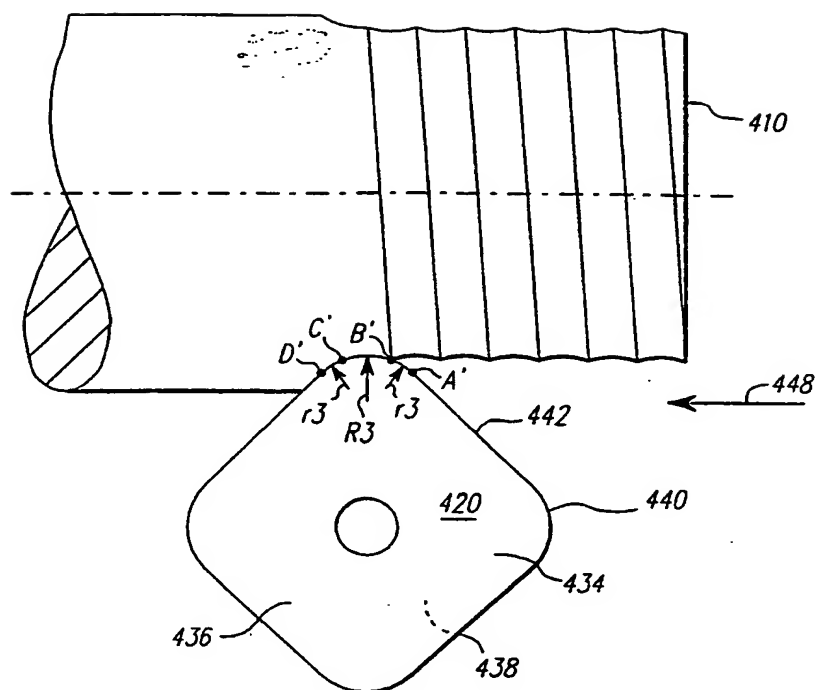


FIG. 8

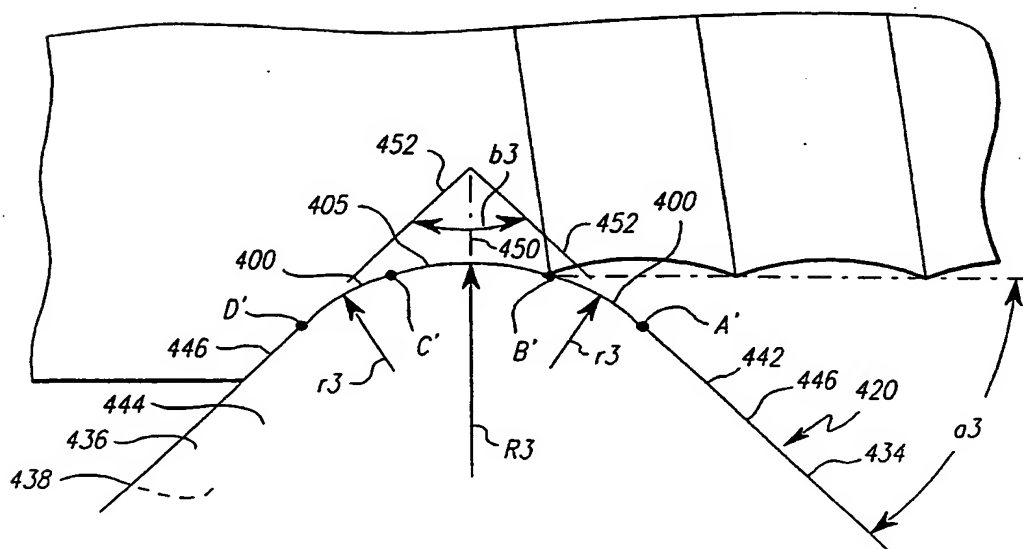


FIG. 9

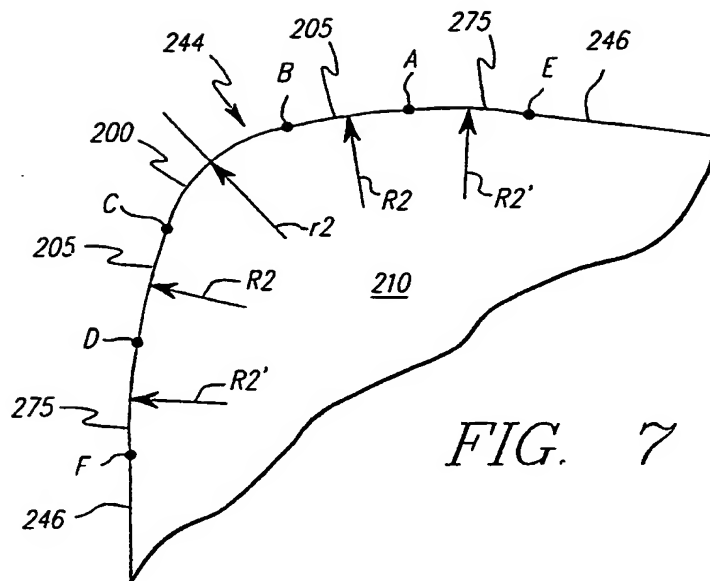


FIG. 7

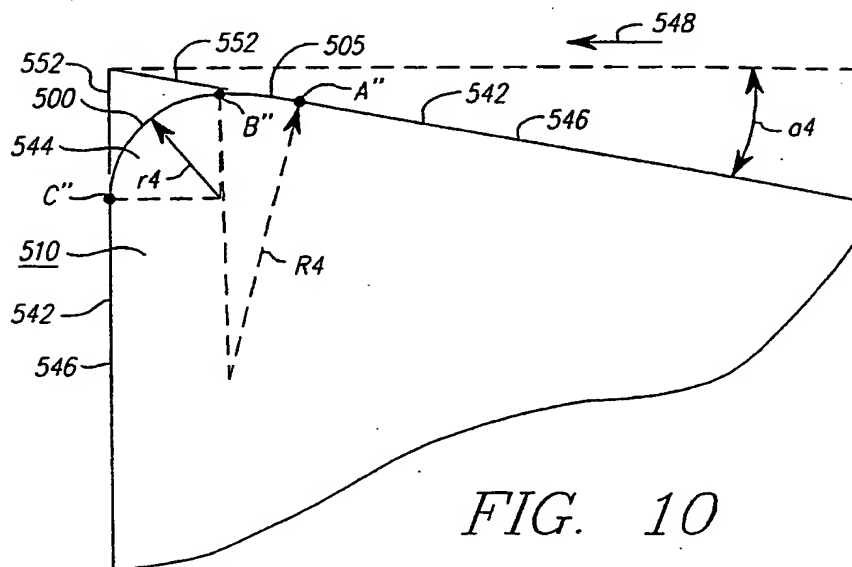


FIG. 10

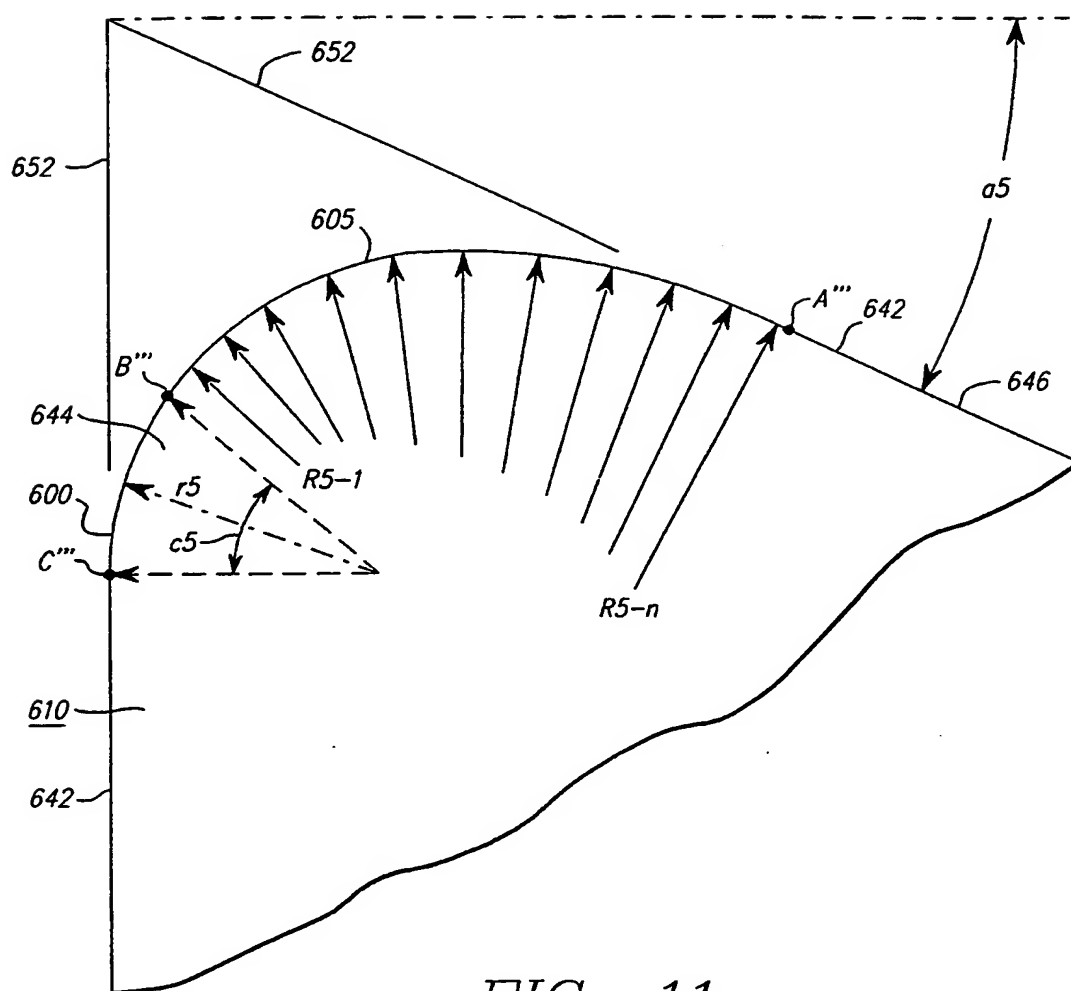


FIG. 11

## INTERNATIONAL SEARCH REPORT

International application No.  
PCT/US 94/04992A. CLASSIFICATION OF SUBJECT MATTER  
IPC 5 B23B27/14

According to International Patent Classification (IPC) or to both national classification and IPC

## B. FIELDS SEARCHED

Minimum documentation searched (classification system followed by classification symbols)  
IPC 5 B23B B23C

Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched

Electronic data base consulted during the international search (name of data base and, where practical, search terms used)

## C. DOCUMENTS CONSIDERED TO BE RELEVANT

Category *	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
X	EP,A,0 489 701 (SANDVIK) 10 June 1992 see column 3, line 30 - line 35; figure 2 ---	1-46
X	PATENT ABSTRACTS OF JAPAN vol. 9, no. 297 (M-432) (2020) 25 November 1985 & JP,A,60 135 104 (TOSHIBA TUNGALOY) 18 July 1985 see abstract ---	1, 12, 24, 25, 34, 42
X	DE,A,26 10 097 (SCHUBERT & SALZER) 29 September 1977 see page 5, line 7 - page 6, line 4; figure 1 ---	1, 12, 24, 25, 34, 42
A	GB,A,2 104 421 (KOMET) 9 March 1983 see page 2, line 46 - line 64; figures 1, 3-5 ---	1
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☒ Further documents are listed in the continuation of box C.☒ Patent family members are listed in annex.

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Date of the actual completion of the international search

23 August 1994

Date of mailing of the international search report

13. 09. 94

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# INTERNATIONAL SEARCH REPORT

International application No.  
PCT/US 94/04992

## C.(Continuation) DOCUMENTS CONSIDERED TO BE RELEVANT

Category *	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
A	US,A,4 214 847 (KRAEMER) 29 July 1980 see column 1, line 65 - column 2, line 2; figure 2 -----	1

# INTERNATIONAL SEARCH REPORT

Information on patent family members

International application No.  
PCT/US 94/04992

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DE-A-2610097	29-09-77	NONE	
GB-A-2104421	09-03-83	AT-B- 388524 BE-A- 893749 CH-A- 657076 FR-A, B 2511905 JP-A- 58040203 NL-A, B, C 8202870 SE-B- 450096 SE-A- 8204211 US-A- 4486127	25-07-89 03-11-82 15-08-86 04-03-83 09-03-83 16-03-83 09-06-87 07-07-82 04-12-84
US-A-4214847	29-07-80	NONE	